

MRI: Speed, Phase, Echo

Zhengguo Tan

Artificial Intelligence in Biomedical Engineering (AIBE)
Friedrich-Alexander-Universität Erlangen-Nürnberg (FAU)

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Outline

Self Introduction

What I have done

- in Frahm lab

- jointly in Frahm & Uecker lab

- in Knoll lab

- Inspirations

- Deep Learning Empowered Image Reconstruction

Summary

Self Introduction

Zhengguo ↔ Jung Gwoh



how to pronounce the chinese name Zheng Guo



The Chinese name "Zheng Guo" is pronounced as "jung gwoh."

The pronunciation of "Zheng" is similar to the English word "jungle," but with a sharper "j" sound at the beginning, like the "s" in "measure." It is followed by a short "uh" sound.

The pronunciation of "Guo" sounds like the English word "go," but with a slight "w" sound at the end. The "o" is pronounced as a short "oh" sound.

Put together, "Zheng Guo" is pronounced as "jung gwoh."

Academic Background

1. Chronologically,

- ▶ 2022 - now, senior postdoc in Prof. Florian Knoll's lab in Erlangen
- ▶ 2019 - 2021, DFG ¹ funded temporary principal investigator ² in Prof. Martin Uecker's lab in University Medical Center Göttingen
- ▶ 2012 - 2016, PhD in Prof. Jens Frahm's lab in Max Planck Institute

¹DFG: Deutsche Forschungsgemeinschaft, <https://www.dfg.de/>

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- ▶ 2012 - 2016, PhD in Prof. Jens Frahm's lab in Max Planck Institute

2. Technically,

- ▶ Pulse sequence programming skill trained by the FLASH inventor
- ▶ Iterative image reconstruction skill trained by the BART inventor
- ▶ Artificial intelligence skill trained by the VarNet inventor

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Collaboration & Teaching

1. Collaboration

- ▶ UHF Predevelopment Team at Siemens
- ▶ Prof. Frederik Laun at University Hospital Erlangen
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- ▶ Pulseq (together with Prof. Moritz Zaiss) for master students
- ▶ Medical Engineering II (blackboard exercises) for bachelor students

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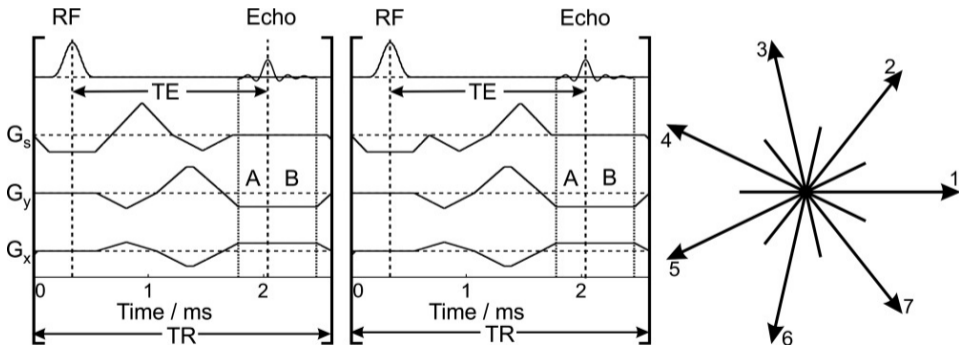
3. Master thesis at FAU

- ▶ Ms. Soundarya Soundarresan
- ▶ Mr. Kai Zhao

What I have done

Real-Time Flow MRI based on Asymmetric-Echo Radial Sampling ³

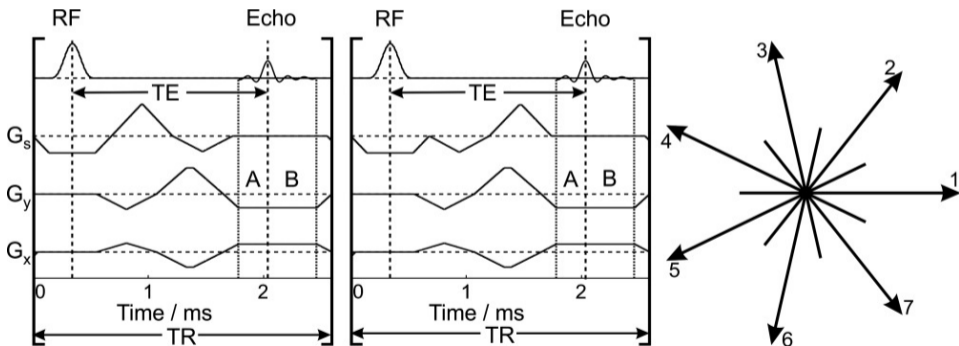
- Interleaved acquisition: 1x flow-compensated ($S = 0$) + 1x flow-encoded ($S = 1$)



³Untenberger M #, Tan Z #, et al. [Advances in real-time phase-contrast flow MRI using asymmetric radial gradient echoes](#). *Magn Reson Med* (2016). # equal contribution

Real-Time Flow MRI based on Asymmetric-Echo Radial Sampling ³

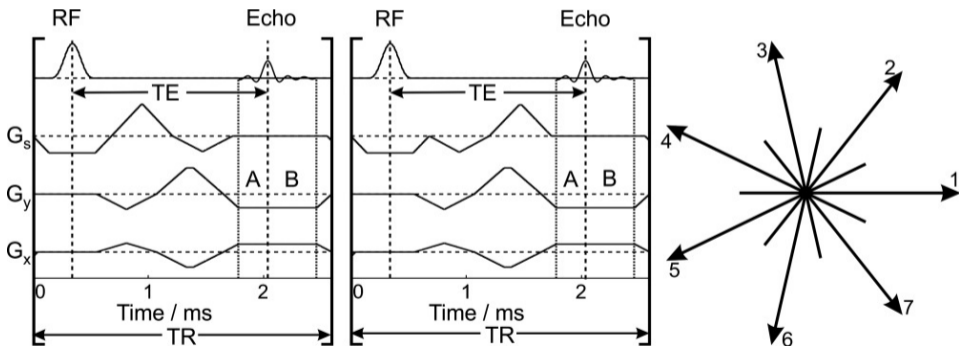
- ▶ Interleaved acquisition: 1x flow-compensated ($S = 0$) + 1x flow-encoded ($S = 1$)
- ▶ Asymmetric-echo readout to reduce TR



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Real-Time Flow MRI based on Asymmetric-Echo Radial Sampling ³

- ▶ Interleaved acquisition: 1x flow-compensated ($S = 0$) + 1x flow-encoded ($S = 1$)
- ▶ Asymmetric-echo readout to reduce TR
- ▶ Temporal resolution: 36 ms per velocity map



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Real-Time Flow MRI: Model-based Reconstruction ^{4,5}

- ▶ Idea: to jointly estimate phase-difference maps

⁴Tan Z, et al. [Model-based reconstruction for real-time phase-contrast flow MRI: Improved spatiotemporal accuracy](#). *Magn Reson Med* (2017).

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Real-Time Flow MRI: Model-based Reconstruction ^{4,5}

- ▶ Idea: to jointly estimate phase-difference maps
- ▶ Solution: to solve a nonlinear least square problem

$$\begin{aligned}\Phi(x) &= \operatorname{argmin}_x \left\| \mathbf{y} - \mathbf{PFC}\{\rho \cdot e^{i\Delta\phi \cdot S}\} \right\|_2^2 + \lambda \|x\|_2^2 \\ x &= (\rho, \Delta\phi, c_1, \dots, c_N)^T\end{aligned}\tag{1}$$

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- ▶ Pros: enable the regularization of phase-difference maps ($\Delta\phi$)

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- ▶ Pros: enable the regularization of phase-difference maps ($\Delta\phi$)
- ▶ Cons: require the implementation of the Jacobian matrix and the balance of partial derivatives

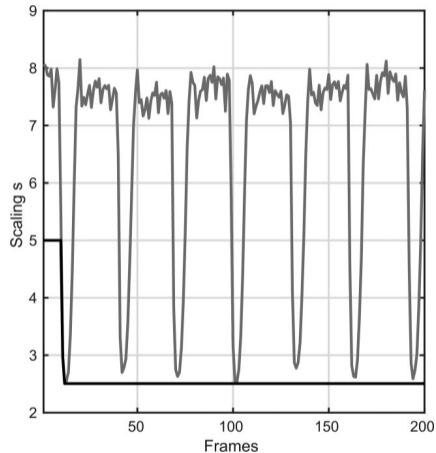
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⁵Wang X, Tan Z, et al. [Physics-based reconstruction methods for MRI](#). *Philos Trans Royal Soc A* (2021).

Balancing Partial Derivatives: Data-Driven Approach ⁶

- ▶ kind of self-gating, like XD-GRASP or GRASP-Pro
- ▶ Solution: to track the scaling value from measured k -space data

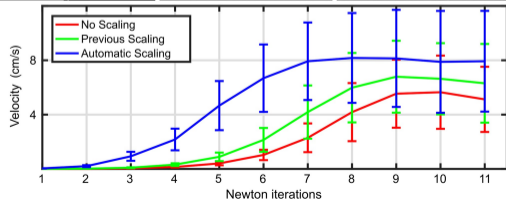
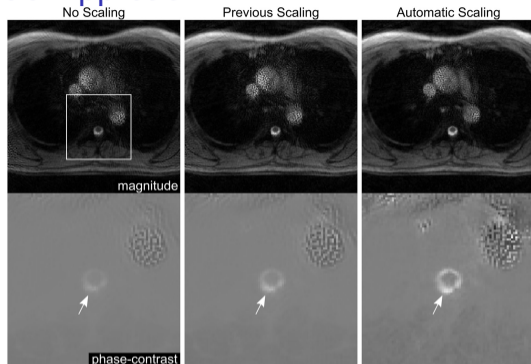
$$s = 0.5 \cdot \frac{\|y_1\|_2 + \|y_2\|_2}{\|y_1 - y_2\|_2} \quad (2)$$



⁶Tan Z, et al. [Model-based reconstruction for real-time phase-contrast flow MRI: Improved spatiotemporal accuracy](#). *Magn Reson Med* (2017).

Balancing Partial Derivatives: Eigenvalue Approach ⁷

1. kind of numerical methods, like batch normalization
2. to compute the matrix norm of the derivative operator



⁷Tan Z, et al. An eigenvalue approach for the automatic scaling of unknowns in model-based reconstructions: Application to real-time phase-contrast flow MRI. *NMR Biomed* (2017).
What I have done in Frahm lab

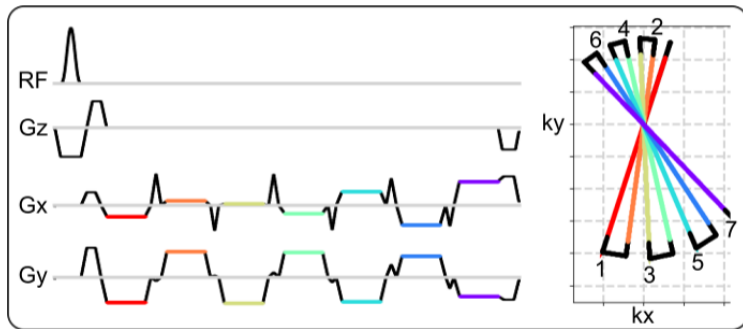
Real-Time Aortic Blood Flow MRI at 36 ms

magnitude images

phase-difference maps

Multi-Echo Radial Sampling^{8,9}

- ▶ use blip gradients to traverse among echoes
- ▶ use spoiler gradients for stack-of-stars volumetric acquisition



⁸Tan Z, et al. *Dynamic water/fat separation and B_0 inhomogeneity mapping – joint estimation using undersampled triple-echo multi-spoke radial FLASH*. *Magn Reson Med* (2019).

⁹Tan Z, et al. *Free-breathing liver fat, R_2^* and B_0 field mapping using multi-echo radial FLASH and regularized model-based reconstruction*. *IEEE Trans Med Imaging* (2023).

Application #1: Free-Breathing Liver Fat & R_2^* Quantification

- ▶ to solve a generalized nonlinear inverse problem

$$\begin{aligned}\Phi(x) &= \operatorname{argmin}_x \|\mathbf{y} - \mathbf{PFCB}(x)\|_2^2 + \lambda R(x) \\ x &= (W, F, R_2^*, f_{B_0}, c_1, \dots, c_N)^T\end{aligned}\tag{3}$$

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- ▶ multi-echo gradient echo signal model

$$B(x) : \rho_m = (W + F \cdot z_m) \cdot e^{-R_2^* \text{TE}_m} \cdot e^{i2\pi f_{B_0} \text{TE}_m}\tag{4}$$

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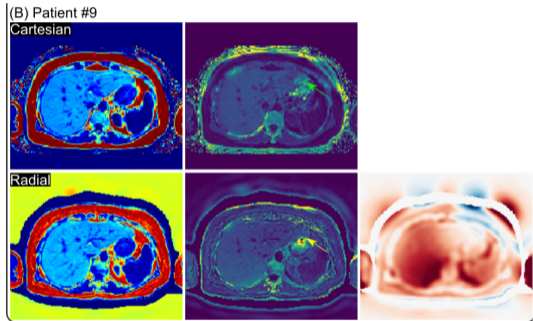
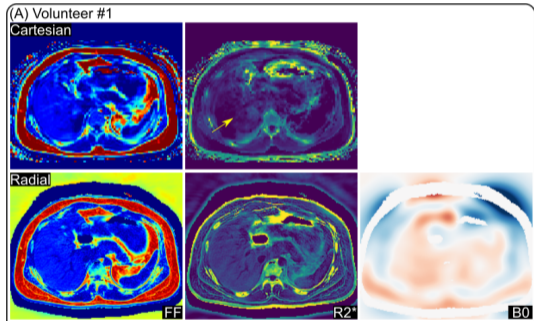
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- ▶ Cons: the field inhomogeneity map (f_{B_0}) is sensitive to initial guess

Application #1: Free-Breathing Liver Fat & R_2^* Quantification



Application #2: Volumetric Brain T_2^* -Weighted Imaging ¹⁰

- ▶ spatial resolution 1 mm isotropic
- ▶ 35 echoes per excitation and 7 shots per partition
- ▶ use linear subspace modeling and reconstruction instead

¹⁰Tan Z, et al. *under review*

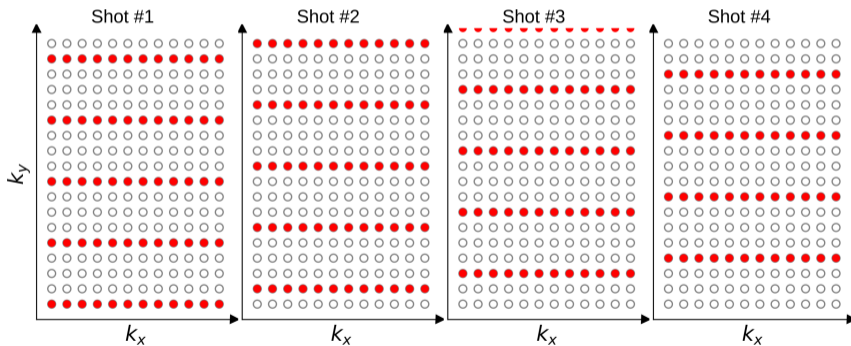
Brain Diffusion MRI at 7 T

► Challenges:

1. Specific Absorption Rate (SAR) is linearly proportional to the square of B_0
2. Shorter T_2 relaxation at 7 T
3. Increased sensitivity to field inhomogeneity, incl. B_0 and B_1

Brain Diffusion MRI State-of-the-Art: MUSE¹¹

- ▶ uses 4-shot interleaved EPI (iEPI), resembling a fully-sampled k -space
- ▶ self-navigated shot-to-shot phase variation estimation
- ▶ limited number of shots has been reported

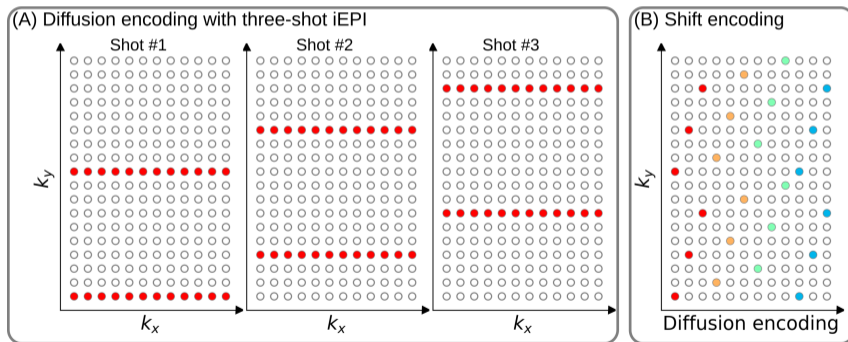


¹¹Chen NK, et al. A robust multi-shot scan strategy for high-resolution diffusion weighted MRI enabled by multiplexed sensitivity-encoding (MUSE). *NeuroImage* (2013).

Undersampled iEPI with k_y Shift Encoding ¹²

- ▶ Acceleration factor per shot:

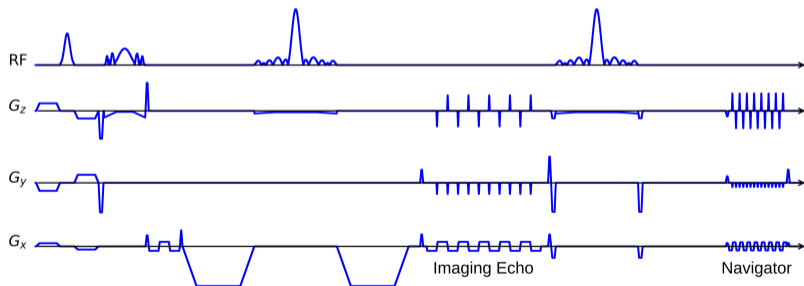
$$R_{\text{shot}} = R_{\text{in-plane}} \times N_{\text{shot}} \quad (5)$$



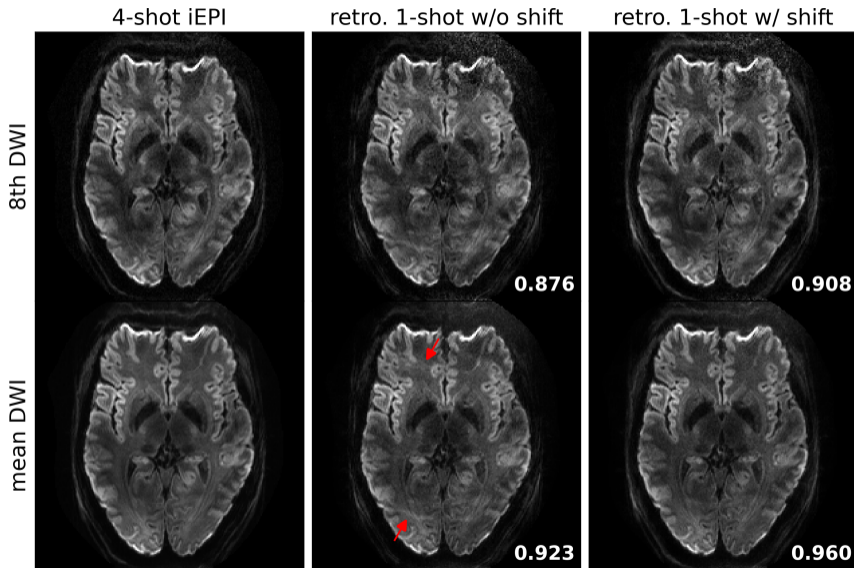
¹²Tan Z, et al. *under review*.

NAViEPI: where iEPI meets rsEPI

- ▶ Navigator-based iEPI with consistent effective ESP between echoes
- ▶ enables:
 1. minimal distortion mismatch between echoes
 2. flexible number of shots
 3. reliable shot-to-shot phase estimation

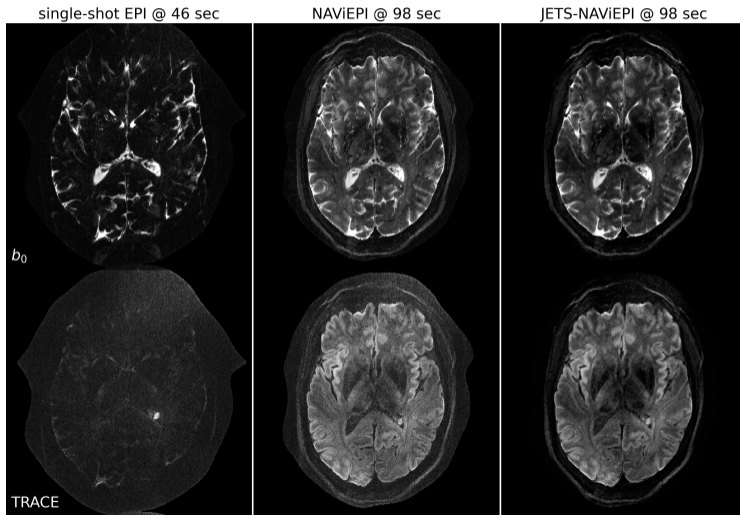


k_y Shifting is Beneficial in Joint k - q -Slice Reconstruction



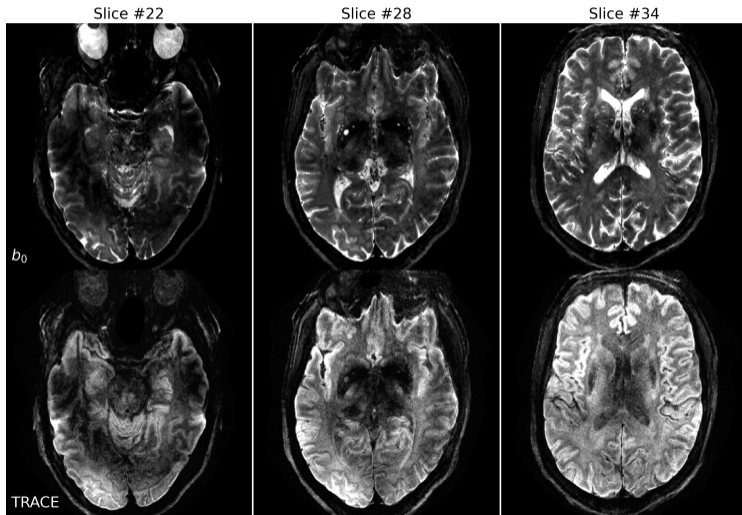
Efficiency of NAViEPI

3-scan trace acquisition with voxel size $0.5 \times 0.5 \times 2.0 \text{ mm}^3$



B_1^+ Field Inhomogeneity Challenge

3-scan trace acquisition with voxel size 0.5 X 0.5 X 2.0 mm³



JETS-NAViEPI: Reproducibility

The screenshot shows a GitHub repository page for 'ZhengguoTan / demo_jets_diffusion_mri_7t'. The repository is public and has 0 stars, 0 forks, and 2 watchers. The main content area displays the README for 'JETS for Diffusion MRI at 7 T', which describes a demonstration on a joint k-q-slice rEonsTruction framework. It mentions the ISMRM 2023 MR-Pub III Competition and provides links for an interactive code demo and data. The commit history shows three recent commits: 'LICENSE' (initial commit, last month), 'README.md' (update README, last month), and 'demo_jets_diffusio...' (add the plot of sampling patterns, 3 weeks ago).

Repository: ZhengguoTan / demo_jets_diffusion_mri_7t

Code Issues Pull requests Actions Projects Security Insights Settings

demo_jets_diffusion_mri_7t Public Pin Unwatch 2 Fork 0 Star 0

main Go to file Add file Code About

Branches Tags

ZhengguoTan add the plot of sampling patterns 3 weeks ago 7

File	Commit Message	Time
LICENSE	Initial commit	last month
README.md	update README	last month
demo_jets_diffusio...	add the plot of sampling patterns	3 weeks ago

README.md

JETS for Diffusion MRI at 7 T

Demonstration on Joint k-q-slice rEonsTruction framework for Shift-encoded (JETS) Diffusion MRI at 7 T

ISMRM 2023

MR-Pub III Competition for the Development of Interactive Open-source Code Demos

- Interactive code demo:
[Open in Colab](#)
- Data:
[DOI: 10.5281/zenodo.7989635](https://doi.org/10.5281/zenodo.7989635)

Readme MIT license Activity 0 stars 2 watching 0 forks

Releases

No releases published
[Create a new release](#)

Packages

No packages published
[Publish your first package](#)

Languages

- Jupyter Notebook 100.0%

Is NAViEPI a Reasonable Approach?

- ▶ In the sub-mm case, the base resolution is 440×440

	Required phase-encoding lines (ETL)		
	1-Shot EPI	4-Shot MUSE	5-Shot NAViEPI
partial Fourier ($\times(6/8)$)		330	
Acceleration ($/R_{\text{in-plane}}$)	110	330	110
Shots ($/N_{\text{shot}}$)	110	≈ 82	22

→ Much reduced spatial distortion with NAViEPI

Inspirations: Speed, Phase, Echo

Max-Planck-Institut für biophysikalische Chemie

MPI bpc News
18. Jahrgang Göttingen Ausgabe No. 9 September 2012

Berichte aus Abteilungen und Forschungsgruppen

Real-time MRI – the ultimate quest for speed

Jens Frahm
Biomedizinische NMR Forschungs GmbH (BioNMR)

Almost 30 years ago we measured the spectra of clinical MRI examinations and changed the way medical magnetic resonance imaging (MRI) to explore new frontiers by studying biological structures and functions in vivo in animals and humans. At that time the typical measuring time of a cross-sectional image was about 3 minutes – or 300,000 milliseconds. This article introduces our recent advances in MRI methodology that offer 30,000-fold acceleration: measuring times of 10 milliseconds or less. The new method allows for dynamic imaging of rapid physiologic processes using real-time MRI scans of typically 10 frames per second.

The lack of this – for a long time unexpected – progress was established in 1985 when our small government-funded group of junior research fellows at this institution received the low-angle shot (FLASH) gradient echo MRI (1,2). This acquisition principle overcame some fundamental measurement physical obstacles and led to an at least 100-fold gain in speed compared to established MRI sequences. The general physical approach and its

medical applications vastly broadened the spectrum of clinical MRI examinations and changed the way medical magnetic resonance imaging (MRI) systems. For the first time, it allowed for three-dimensional MRI and provided dynamic brain studies using ECG-triggered cine acquisitions. In retrospect, the FLASH success strongly stimulated worldwide academic interest in both MRI methods and in their clinical diagnosis and translational biomedical research. Prominent examples of subsequent breakthroughs are developments in functional magnetic resonance imaging (fMRI) and dynamic MRI, and in motion-based magnetic resonance imaging (MRI) and cardiac MRI.

Nevertheless, the original measuring time of a single high-quality image remained limited to at least a few hundred milliseconds. This is mainly because the MRI raw data typically requires up to 256 individual experiments with complementary spatial encodings. Our new concept therefore enhances the following idea: While FLASH acquisitions require the time for a single experiment to about 2 to 3 milliseconds, one better acceleration must rely on a reduced number of experiments, for example from 256 to only about 10. Indeed, our current advances combine physical and mathematical strategies that drastically minimize the raw data necessary for reconstructing meaningful image or frame of an MRI movie – a scenario typically described as “undersampling”.

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The lack of this – for a long time unexpected – progress was established in 1985 when our small government-funded group of junior research fellows at this institute received the low-angle shot (FLASH) gradient echo MRI (1,2). This acquisition principle circumvented some fundamental in-measurable physical obstacles and led to at least 100-fold gain in speed compared to established MRI sequences. The general physical approach and its

immediate applications vastly broadened the spectrum of clinical MRI examinations and changed the way medical research teams developed their MRI systems. For the first time, it allowed for three-dimensional MRI and provided dynamic brain studies using ECG-triggered cine acquisitions. In retrospect, the FLASH success strongly stimulated worldwide academic interest in both MRI methods and in use for clinical diagnosis and translational biomedical research. Prominent examples of subsequent breakthroughs and developments in human research were such as functional brain mapping and diffusion-based nerve fiber tractography.

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Irithal

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Magnetic Resonance in Medicine HIGHLIGHTS

Q&As with Authors of Editor's Picks

Kawin Setsompop
The quest for speed

Profile of ISMRM President
Jim Pipe

Erwin Hahn
AN INTERVIEW BY DAVID FEINBERG

ISMRM ONE WILEY August 2015 - April 2016

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multiscale applications vastly broadened the spectrum of clinical MRI examinations and changed the way medical research teams developed their MRI systems. For the first time, it allowed for three-dimensional MRI and provided dynamic brain studies using ECG-triggered cine acquisitions. In retrospect, the FLASH success strongly stimulated worldwide academic interest in both MRI methods and in use for clinical diagnosis and translational biomedical research. Prominent examples of subsequent breakthroughs and developments in human research were such as functional brain imaging and diffusion-based nerve fiber tractography.

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Magnetic Resonance in Medicine HIGHLIGHTS

Penny Gowland
 Visualizing the body in action

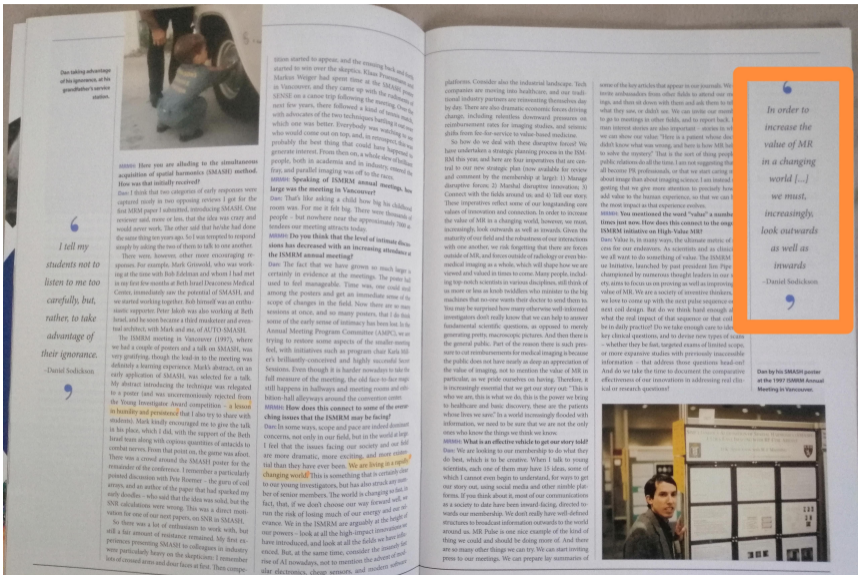
Daniel Sodickson
 Connecting MR in a changing world

Editor's Picks

Al Macovski
 An interview by Graham Wright

ISMRM ONE WILEY March 2017 - April 2018

Connecting MR in a changing world: Look outwards & inwards



Dan taking advantage of his ignorance, at the grandfather's service station.



I tell my students not to listen to me too carefully, but, rather, to take advantage of their ignorance.

-Daniel Sodickson

In order to increase the value of MR in a changing world [...] we must, increasingly, look outwards as well as inwards

-Daniel Sodickson

Dan by his SMASH poster at the 1997 ISMRM Annual Meeting in Vancouver.



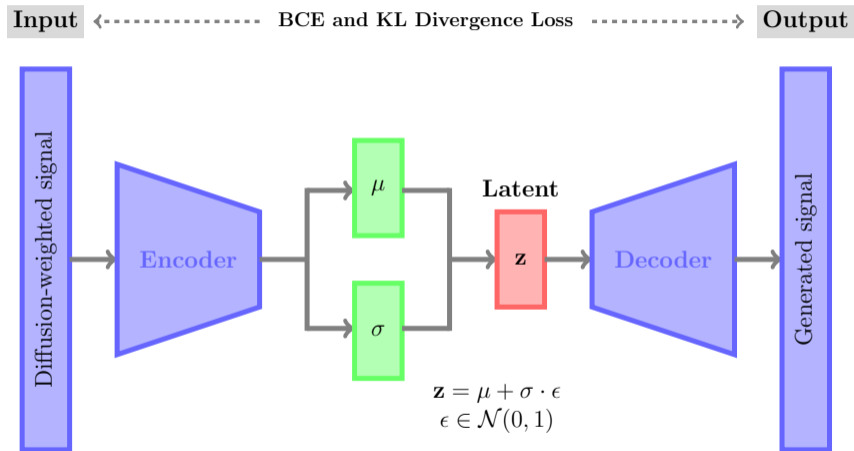
Deep Learning: Any Novelty or Significance?

- ▶ Trustworthy
- ▶ Explainable
- ▶ Robust
- ▶ Data-Efficiency

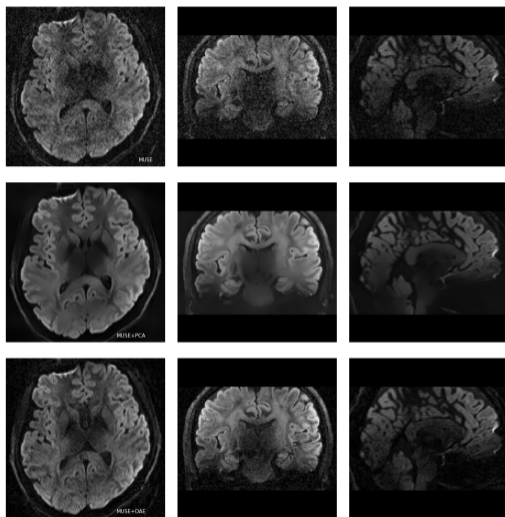
Deep Learning: Any Novelty or Significance?

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 - ▶ Data-Efficiency
-
- ▶ nonlinear \rightarrow linear \rightarrow nonlinear
 - ✓ Deep learning frameworks offer powerful optimizers!

Preliminary Work on Deep Learning: AutoEncoder

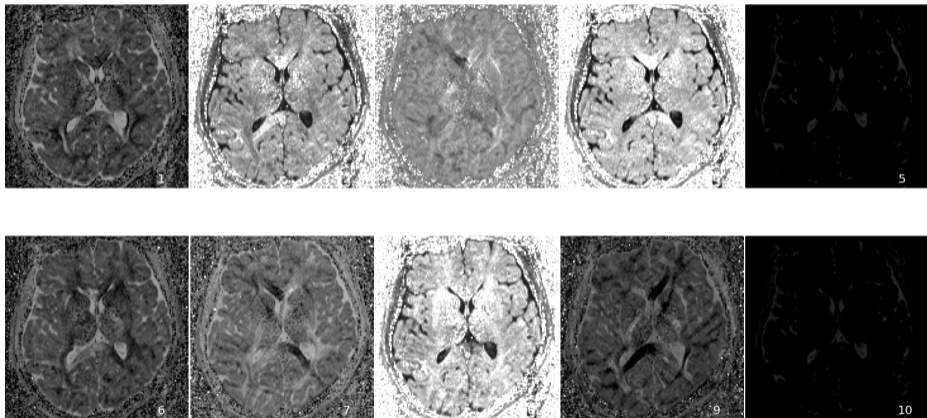


Preliminary Work on Deep Learning: 1.2 mm Isotropic Resolution ¹³



¹³Soundarresan S, **Tan Z**, et al. *submitted to ESMRMB*

Preliminary Work on Deep Learning: Latent Signal



Summary

Thank You for Your Attention!

1. This talk won't be possible without these great people:
 - ▶ Dr. Jens Frahm and his team
 - ▶ Dr. Martin Uecker and his team
 - ▶ Dr. Florian Knoll and his team
 - ▶ Dr. Robin Heidemann
 - ▶ Dr. Patrick Liebig
 - ▶ Dr. Frederik Laun
 - ▶ Ms. Soundarya Soundarresan

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 - ▶ Ms. Soundarya Soundarresan
2. Thank you for your attention again.